

EAST Search History**EAST Search History (Prior Art)**

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	1252	(position location) same (movement maneuver travel) same (object obstacle) same (area zoone region) same map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/09/13 11:18
L2	22	(position location) same (movement maneuver travel) same (object obstacle) same (area zoone region) same map same control same (circle radius) same (distance range)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/09/13 11:25
L3	63	(position location) same (movement maneuver travel) same (object obstacle) same (area zoone region) same map and (701/23,24,25,26,28 700/245).cccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/09/13 11:29

EAST Search History (I nterference)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L5	0	(robot and (mic microphone) and (imag\$3) and voice and (position location) and (movement maneuver travel) and (object obstacle) and (set \$4 near6 (area zoone region)) and surface and map).clm.	USPAT; UPAD	OR	ON	2010/09/13 13:21
L6	0	(robot and (mic microphone) and (imag\$3) and voice and (position location) and (movement maneuver travel) and (object obstacle) and (set \$4 near6 (area zoone region)) and surface and map).clm. and (701/23,24,25,26,28 700/245).cccls.	USPAT; UPAD	OR	ON	2010/09/13 13:22

9/ 13/ 2010 1:22:44 PM
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 Robot Control Device, Robot Control method and program.wsp**

